
peakingduck Documentation

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ABOUT

Peaking identification is crucial for gamma spectroscopy and nuclear analysis. Conventional methods (although included) are not great at finding peaks in areas of low statistics and often fail for multiplet identification (overlapping peaks). A new method involving deep learning methods has been developed to improve both precision and recall of peaks. This library contains some traditional algorithms for peak identification and some neural networks used for more modern approaches. The intention is to provide further analysis in the future (peak fitting, background subtraction, etc) but for the minute just focuses on peak identification. This can also be extended (in theory) to any 1 dimension data set containing labelled peaks.

**CHAPTER
TWO**

STATUS

Very much a work in progress, but is expected to have the first version (0.0.1) ready for release in 2 months.

BUILDING

It is header only C++ so nothing to build (only unit tests) if using it in C++. If you want python bindings enabled then it needs building (default will build them), as below.

```
git clone --recursive -j8 https://github.com/fispact/peakingduck
cd peakingduck
mkdir build
cd build
cmake -DCMAKE_BUILD_TYPE=Release -DBUILD_PY_BINDINGS=ON ..
make -j4```
```

Note: Project uses cmake (> 3.2) to build peaking duck.

3.1 Installation

3.2 1D Data Processing

3.3 Peak Finding

3.4 Extending in C++

3.5 Extending with Python

3.6 peakingduck Python Package

Peaking duck library using pybind11

ToDo: write

A list:

- Entry 1
- Entry 2

3.6.1 peakingduck.core module

class `peakingduck.core.ChunkedSimplePeakFinder` (*threshold=0.05, nchunks=10*)
Bases: `PEAKINGDUCK.core.IPeakFinder`
Breaks the spectrum up into `nchunks` applying the threshold relative to that chunk
find (*self: PEAKINGDUCK.core.IPeakFinder, arg0: PEAKINGDUCK.core.NumericalData*) →
List[`PEAKINGDUCK.core.PeakInfo`]
Identifies potential peaks in the data

class `peakingduck.core.ChunkedThresholdPeakFilter`
Bases: `PEAKINGDUCK.core.IProcess`
Simple threshold local/chunked peak filter

class `peakingduck.core.GlobalThresholdPeakFilter`
Bases: `PEAKINGDUCK.core.IProcess`
Simple threshold global peak filter

class `peakingduck.core.Histogram`
Bases: `pybind11_builtins.pybind11_object`
Represents a basic 1D histogram
Energies vs values.
property X
property Y

class `peakingduck.core.HistogramChannelBased`
Bases: `pybind11_builtins.pybind11_object`
Represents a basic 1D histogram
Channels vs values.
property X
property Y

class `peakingduck.core.IPeakFinder`
Bases: `pybind11_builtins.pybind11_object`
Interface for peak finding algorithms
Operates on numerical data (filtered or unfiltered). Never mutates the input (always const process).
Returns A list of peaks
Return type `PeakList`
find (*self: PEAKINGDUCK.core.IPeakFinder, arg0: PEAKINGDUCK.core.NumericalData*) →
List[`PEAKINGDUCK.core.PeakInfo`]
Identifies potential peaks in the data

class `peakingduck.core.IProcess`
Bases: `pybind11_builtins.pybind11_object`
Interface for all process algorithms
Operates on numerical data. Never mutates the input (always const process).
Returns A new numerical array.

go (*self*: *PEAKINGDUCK.core.IProcess*, *arg0*: *PEAKINGDUCK.core.NumericalData*) → *PEAKINGDUCK.core.NumericalData*

class *peakingduck.core.IProcessManager*

Bases: *pybind11_builtins.pybind11_object*

A general process manager interface

append (*self*: *PEAKINGDUCK.core.IProcessManager*, *arg0*: *PEAKINGDUCK.core.IProcess*) → *PEAKINGDUCK.core.IProcessManager*

reset (*self*: *PEAKINGDUCK.core.IProcessManager*) → *None*

run (*self*: *PEAKINGDUCK.core.IProcessManager*, *arg0*: *PEAKINGDUCK.core.NumericalData*) → *PEAKINGDUCK.core.NumericalData*

class *peakingduck.core.IntegerData*

Bases: *pybind11_builtins.pybind11_object*

Represents a 1-dimensional data structure of ints (basically a 1D Eigen array)

Dynamic array - most use cases will be determined at runtime (I am assuming). We don't want anyone to know we are using Eigen beyond this file, since (in theory) it should make it easier to change library if need be. We only really need the array datastructure from Eigen and not much else and instead of reinventing the wheel, we wrap Eigen array.

We wrap this with private inheritance on the Eigen type but there are a lot of methods to expose, easy to add when/if we need them.

Eigen array is pretty good, it has things like `sqrt`, `exp` on array coefficients, but we need to extend this to other functions, so we use CRTP to do this.

For all of this, you may ask why not just use Eigen and use an alias? Well for one, we don't need all of Eigen just the array, and not all of the array type (we require a simpler interface). Additionally, at some point we may wish to use another data structure as `std::array` for example. In this case we just change the `NumericalData` class to wrap that instead. If we change the alias this could break existing interfaces and APIs, causing big changes later on. Since this datastructure is fundamental to everything we need to make sure that we have this sorted properly first!

from_list (*self*: *PEAKINGDUCK.core.IntegerData*, *arg0*: *List[int]*) → *None*

maxCoeff (*self*: *PEAKINGDUCK.core.IntegerData*) → *int*

minCoeff (*self*: *PEAKINGDUCK.core.IntegerData*) → *int*

ramp (*self*: *PEAKINGDUCK.core.IntegerData*, *arg0*: *int*) → *PEAKINGDUCK.core.IntegerData*

A simple function for filtering values above a certain threshold (\geq). This is useful to remove entries that are negative for example.

Returns A new array.

rampInPlace (*self*: *PEAKINGDUCK.core.IntegerData*, *arg0*: *int*) → *PEAKINGDUCK.core.IntegerData*

A simple function for filtering values above a certain threshold (\geq). This is useful to remove entries that are negative for example.

Mutates underlying data.

reverse (*self*: *PEAKINGDUCK.core.IntegerData*) → *numpy.ndarray[int32[m, 1]]*

reverseInPlace (*self*: *PEAKINGDUCK.core.IntegerData*) → *None*

slice (*self*: *PEAKINGDUCK.core.IntegerData*, *arg0*: *int*, *arg1*: *int*) → *PEAKINGDUCK.core.IntegerData*

sum (*self*: *PEAKINGDUCK.core.IntegerData*) → *int*

`to_list` (*self*: *PEAKINGDUCK.core.IntegerData*) → List[int]

class `peakingduck.core.MovingAveragePeakFilter`

Bases: `PEAKINGDUCK.core.IProcess`

Simple moving average peak filter

class `peakingduck.core.MovingAverageSmoother`

Bases: `PEAKINGDUCK.core.IProcess`

Simple moving average smoother

Can we support window size given at compile time too? It would certainly help with unit tests.

class `peakingduck.core.NumericalData`

Bases: `pybind11_builtins.pybind11_object`

Represents a 1-dimensional data structure of floats (basically a 1D Eigen array)

Dynamic array - most use cases will be determined at runtime (I am assuming). We don't want anyone to know we are using Eigen beyond this file, since (in theory) it should make it easier to change library if need be. We only really need the array datastructure from Eigen and not much else and instead of reinventing the wheel, we wrap Eigen array.

We wrap this with private inheritance on the Eigen type but there are a lot of methods to expose, easy to add when/if we need them.

Eigen array is pretty good, it has things like `sqrt`, `exp` on array coefficients, but we need to extend this to other functions, so we use CRTP to do this.

For all of this, you may ask why not just use Eigen and use an alias? Well for one, we don't need all of Eigen just the array, and not all of the array type (we require a simpler interface). Additionally, at some point we may wish to use another data structure as `std::array` for example. In this case we just change the `NumericalData` class to wrap that instead. If we change the alias this could break existing interfaces and APIs, causing big changes later on. Since this datastructure is fundamental to everything we need to make sure that we have this sorted properly first!

LLS (*self*: *PEAKINGDUCK.core.NumericalData*) → `PEAKINGDUCK.core.NumericalData`

$\log(\log(\sqrt{\text{value} + 1} + 1) + 1)$

Returns A new array.

LLSInPlace (*self*: *PEAKINGDUCK.core.NumericalData*) → `PEAKINGDUCK.core.NumericalData`

$\log(\log(\sqrt{\text{value} + 1} + 1) + 1)$

Changes the underlying array.

exp (*self*: *PEAKINGDUCK.core.NumericalData*) → `numpy.ndarray[float64[m, 1]]`

from_list (*self*: *PEAKINGDUCK.core.NumericalData*, *arg0*: List[float]) → None

inverseLLS (*self*: *PEAKINGDUCK.core.NumericalData*) → `PEAKINGDUCK.core.NumericalData`

$\exp(\exp(\sqrt{\text{value} + 1} + 1) + 1)$

Returns A new array.

inverseLLSInPlace (*self*: *PEAKINGDUCK.core.NumericalData*) → `PEAKINGDUCK.core.NumericalData`

$\exp(\exp(\sqrt{\text{value} + 1} + 1) + 1)$

Changes the underlying array.

log (*self*: *PEAKINGDUCK.core.NumericalData*) → `numpy.ndarray[float64[m, 1]]`

maxCoeff (*self*: *PEAKINGDUCK.core.NumericalData*) → float

mean (*self*: *PEAKINGDUCK.core.NumericalData*) → float

midpoint (*self*: *PEAKINGDUCK.core.NumericalData*, *arg0*: *int*) → *PEAKINGDUCK.core.NumericalData*

For each element calculate the midpoint value from the adjacent elements at a given order.

Take the i-order point and the i+order point and determine the average = (array[i-j]+array[i+j])/2.0. End points are not counted (stay as original) - max(0, i-j) and min(i+j, len(array))

Examples

Given an array: [1, 4, 6, 2, 4, 2, 5]

- we have the midpoints for order 0: [1, 4, 6, 2, 4, 2, 5]
- we have the midpoints for order 1: [1, 3.5, 3, 5, 2, 4.5, 5]
- we have the midpoints for order 2: [1, 4, 2.5, 3, 5.5, 2, 5]
- we have the midpoints for order 3: [1, 4, 6, 3, 4, 2, 5]
- we have the midpoints for order 4+: [1, 4, 6, 2, 4, 2, 5]

Returns A new array.

midpointInPlace (*self*: *PEAKINGDUCK.core.NumericalData*, *arg0*: *int*) → *PEAKINGDUCK.core.NumericalData*

For each element calculate the midpoint value from the adjacent elements at a given order.

Mutates underlying array.

See also:

`peakingduck.core.NumericalData.midpoint()`

minCoeff (*self*: *PEAKINGDUCK.core.NumericalData*) → float

pow (*self*: *PEAKINGDUCK.core.NumericalData*, *arg0*: *float*) → `numpy.ndarray[float64[m, 1]]`

ramp (*self*: *PEAKINGDUCK.core.NumericalData*, *arg0*: *float*) → *PEAKINGDUCK.core.NumericalData*

A simple function for filtering values above a certain threshold (>=). This is useful to remove entries that are negative for example.

Returns A new array.

rampInPlace (*self*: *PEAKINGDUCK.core.NumericalData*, *arg0*: *float*) → *PEAKINGDUCK.core.NumericalData*

A simple function for filtering values above a certain threshold (>=). This is useful to remove entries that are negative for example.

Mutates underlying data.

reverse (*self*: *PEAKINGDUCK.core.NumericalData*) → `numpy.ndarray[float64[m, 1]]`

reverseInPlace (*self*: *PEAKINGDUCK.core.NumericalData*) → None

slice (*self*: *PEAKINGDUCK.core.NumericalData*, *arg0*: *int*, *arg1*: *int*) → *PEAKINGDUCK.core.NumericalData*

snip (**args*, ***kwargs*)

Overloaded function.

1. `snip(self: PEAKINGDUCK.core.NumericalData, arg0: List[int]) -> PEAKINGDUCK.core.NumericalData`

Sensitive Nonlinear Iterative Peak (SNIP) algorithm for estimating backgrounds

ref needed here:

Allows any form of iterations given an iterator

Returns: A new array.

2. `snip(self: PEAKINGDUCK.core.NumericalData, niterations: int = 20) -> PEAKINGDUCK.core.NumericalData`

Sensitive Nonlinear Iterative Peak (SNIP) algorithm for estimating backgrounds ref needed here.

Does via increasing window only (ToDo: need to allow decreasing window)

Deprecate this!

Returns: A new array.

`sqrt (self: PEAKINGDUCK.core.NumericalData) -> numpy.ndarray[float64[m, 1]]`

`square (self: PEAKINGDUCK.core.NumericalData) -> numpy.ndarray[float64[m, 1]]`

`stddev (self: PEAKINGDUCK.core.NumericalData, ddof: int = 0) -> float`

`sum (self: PEAKINGDUCK.core.NumericalData) -> float`

`to_list (self: PEAKINGDUCK.core.NumericalData) -> List[float]`

class `peakingduck.core.PeakInfo`

Bases: `pybind11_builtins.pybind11_object`

Simple struct for holding peak info.

value

value, i.e. count or flux.

index

the corresponding index/channel of the data.

property index

property value

class `peakingduck.core.PySimpleProcessManager (processes=None)`

Bases: `PEAKINGDUCK.core.IProcessManager`

Instead of using the C++ SimpleProcessManager we make a python native version to avoid ref counting issues

Easy to extend also.

`append (self: PEAKINGDUCK.core.IProcessManager, arg0: PEAKINGDUCK.core.IProcess) -> PEAKINGDUCK.core.IProcessManager`

`run (self: PEAKINGDUCK.core.IProcessManager, arg0: PEAKINGDUCK.core.NumericalData) -> PEAKINGDUCK.core.NumericalData`

class `peakingduck.core.SavitzkyGolaySmoother (windowsize, order=2)`

Bases: `PEAKINGDUCK.core.IProcess`

`go (self: PEAKINGDUCK.core.IProcess, arg0: PEAKINGDUCK.core.NumericalData) -> PEAKINGDUCK.core.NumericalData`

class `peakingduck.core.ScipyPeakFinder (threshold=2.0, smoothsize=1001)`

Bases: `PEAKINGDUCK.core.IPeakFinder`

Wrapper for scipy peak finder

TODO: pass smoother to constructor not just window size

find (*self*: *PEAKINGDUCK.core.IPeakFinder*, *arg0*: *PEAKINGDUCK.core.NumericalData*) → List[*PEAKINGDUCK.core.PeakInfo*]
Identifies potential peaks in the data

class *peakingduck.core.SimplePeakFinder*

Bases: *PEAKINGDUCK.core.IPeakFinder*

find (*self*: *PEAKINGDUCK.core.SimplePeakFinder*, *arg0*: *PEAKINGDUCK.core.NumericalData*) → List[*PEAKINGDUCK.core.PeakInfo*]

class *peakingduck.core.SimpleProcessManager*

Bases: *PEAKINGDUCK.core.IProcessManager*

A simple process manager

append (*self*: *PEAKINGDUCK.core.SimpleProcessManager*, *arg0*: *PEAKINGDUCK.core.IProcess*) → *PEAKINGDUCK.core.IProcessManager*

reset (*self*: *PEAKINGDUCK.core.SimpleProcessManager*) → None

run (*self*: *PEAKINGDUCK.core.SimpleProcessManager*, *arg0*: *PEAKINGDUCK.core.NumericalData*) → *PEAKINGDUCK.core.NumericalData*

class *peakingduck.core.SpectrumChannelBased*

Bases: *PEAKINGDUCK.core.HistogramChannelBased*

Represents a basic 1D histogram

Channels vs values.

estimateBackground (*self*: *PEAKINGDUCK.core.SpectrumChannelBased*, *arg0*: List[int]) → *PEAKINGDUCK.core.NumericalData*

removeBackground (*self*: *PEAKINGDUCK.core.SpectrumChannelBased*, *arg0*: List[int]) → None

class *peakingduck.core.SpectrumEnergyBased*

Bases: *PEAKINGDUCK.core.Histogram*

Represents a basic 1D histogram

Energies vs values.

estimateBackground (*self*: *PEAKINGDUCK.core.SpectrumEnergyBased*, *arg0*: List[int]) → *PEAKINGDUCK.core.NumericalData*

removeBackground (*self*: *PEAKINGDUCK.core.SpectrumEnergyBased*, *arg0*: List[int]) → None

class *peakingduck.core.WeightedMovingAverageNative* (*windowSize*)

Bases: *PEAKINGDUCK.core.IProcess*

We can extend the C++ classes here This is an example

go (*data*)

if N=1, weights=[1] -> [1/N] if N=2, weights=[1,1] -> [1/2, 1/2] if N=3, weights=[1,2,1] -> [1/4, 2/4, 1/4]
if N=4, weights=[1,2,2,1] -> [1/6, 2/6, 2/6, 1/6] if N=5, weights=[1,2,3,2,1] -> [1/9, 2/9, 3/9, 2/9, 1/9] ...

weights=[1,2,..., ceil(n/2), ..., 2, 1] = [1, ..., ceil(n/2)] + [ceil(n/2), ..., 1] weights = weights/sum(weights)

class *peakingduck.core.WeightedMovingAverageSmoother*

Bases: *PEAKINGDUCK.core.IProcess*

Simple moving average smoother

Uses weights determined, with *windowSize* = N

- if N=1, weights=[1] -> [1/N]
- if N=2, weights=[1,1] -> [1/2, 1/2]
- if N=3, weights=[1,2,1] -> [1/4, 2/4, 1/4]
- if N=4, weights=[1,2,2,1] -> [1/6, 2/6, 2/6, 1/6]
- if N=5, weights=[1,2,3,2,1] -> [1/9, 2/9, 3/9, 2/9, 1/9]
- ...

class `peakingduck.core.WindowPeakFinder` (*threshold=2.0, ninner=0, nouter=40, include_point=False, enforce_maximum=False, use_grad=False*)

Bases: `PEAKINGDUCK.core.IPeakFinder`

A bespoke window method peak finder

find (*data, *args, **kwargs*)

Takes npoints either side of bin for each bin in histogram to get mean and stddev with and without that bin

Doesn't use the gradient yet, but we should enable this

`peakingduck.core.combine` (*arg0: PEAKINGDUCK.core.NumericalData, arg1: PEAKINGDUCK.core.NumericalData*) → `PEAKINGDUCK.core.NumericalData`

`peakingduck.core.peakwindow` ()

`window` (*values: PEAKINGDUCK.core.NumericalData, centerindex: int, nouter: int = 5, ninner: int = 0, includeindex: bool = True*) -> `PEAKINGDUCK.core.NumericalData`

`peakingduck.core.window` (*values: PEAKINGDUCK.core.NumericalData, centerindex: int, nouter: int = 5, ninner: int = 0, includeindex: bool = True*) → `PEAKINGDUCK.core.NumericalData`

3.6.2 peakingduck.io module

`peakingduck.io.from_csv` (*arg0: PEAKINGDUCK.core.SpectrumEnergyBased, arg1: str*) → None

Deserialization method for histogram

Assumes delimited text data in column form of:

```
channel, lowerenergy, upperenergy, count
```

3.6.3 peakingduck.plotting module

class `peakingduck.plotting.LinePlotAdapter`

Bases: `peakingduck.plotting.plotadaptor.PlotAdapter`

lineplot (*x, y, datalabel="", xlabel="", ylabel="", logx=False, logy=False, overlay=True*)

class `peakingduck.plotting.PlotAdapter`

Bases: `object`

Wraps the Matplotlib plotter

addlegend (*location*)

property engine

The plotter engine

property enginename

The name of the plotting engine

grid (*show=True*)**newcanvas** (**args, **kwargs*)**show** ()

peakingduck.plotting.**getplotvalues** (*x, y*)

Matplotlib hist is slow. Use a hist like plot with conventional line plot

3.6.4 peakingduck.util module

peakingduck.util.**get_window** (*values: List[float], centerindex: int, nouter: int = 5, ninner: int = 0, includeindex: bool = True*) → List[float]

Given a list of values take nouter points either side of the index given and ignore ninner points.

Examples

```
>>> get_window([8, 2, 5, 2, 6, 6, 9, 23, 12], 4, 3, 0, True)
[2, 5, 2, 6, 6, 9, 23]
>>> get_window([8, 2, 5, 2, 6, 6, 9, 23, 12], 4, 3, 0, False)
[2, 5, 2, 6, 9, 23]
>>> get_window([8, 2, 5, 2, 6, 6, 9, 23, 12], 4, 3, 1, True)
[2, 5, 6, 9, 23]
>>> get_window([8, 2, 5, 2, 6, 6, 9, 23, 12], 4, 3, 1, False)
[2, 5, 9, 23]
```

Therefore:

- ninner >= 0
- ninner <= nouter
- index >= nouter
- index < values.size()

It will clip at (0, len(values))

3.7 peakingduck Header Only Library

Defines the full library. A single header file for whole library

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```
class peakingduck::peakingduck::PeakingDuckDBConnectionInvalidException : public peakingduck::PeakingDuckDBConnectionInvalidException {
    #include <exceptions.hpp>
    Database connection exception PeakingDuckDBConnectionInvalidException Throw when issues with attempting to connect to the database.
}
```

Public Functions

```
PeakingDuckDBConnectionInvalidException (std::string text)
~PeakingDuckDBConnectionInvalidException ()
const char *what () const
```

Protected Attributes

```
std::string _what
```

```
class peakingduck::peakingduck::PeakingDuckException : public std::exception
#include <exceptions.hpp> Base level exception PeakingDuckException Should be extended with subclasses.
Subclassed by peakingduck::PeakingDuckDBConnectionInvalidException, peaking-
duck::PeakingDuckFileFormatReadException, peakingduck::PeakingDuckMapKeyNotFoundException
```

Public Functions

```
PeakingDuckException (std::string text)
~PeakingDuckException ()
const char *what () const
```

Protected Attributes

```
std::string _what
```

```
class peakingduck::peakingduck::PeakingDuckFileFormatReadException : public peakingduck::PeakingDuckException
#include <exceptions.hpp> File Format exception PeakingDuckFileFormatReadException Throw when issues
with file formatting (reading)
```

Public Functions

```
PeakingDuckFileFormatReadException (std::string text)
~PeakingDuckFileFormatReadException ()
const char *what () const
```

```
class peakingduck::peakingduck::PeakingDuckMapKeyNotFoundException : public peakingduck::PeakingDuckException
#include <exceptions.hpp> Key lookup exception PeakingDuckMapKeyNotFoundException Throw when issues
when cannot find a key by value (std::map)
```

Public Functions

```

PeakingDuckMapKeyNotFoundException (std::string text)
~PeakingDuckMapKeyNotFoundException ()
const char *what () const

```

3.7.1 peakingduck::constants namespace

Defines the constants (mathematical and physical) of the library.

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```
constexpr const double peakingduck::constants::PI = units::constants::pi
```

3.7.2 peakingduck::core namespace

Defines all core parts of the library (algorithms, data structures).

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```

using peakingduck::core::Array1D = Eigen::Array<Scalar, Size, 1>
using peakingduck::core::Array1Di = Array1D<int>
using peakingduck::core::Array1Df = Array1D<float>
using peakingduck::core::Array1Dd = Array1D<double>
using peakingduck::core::DefaultType = double
using peakingduck::core::PeakList = std::vector<PeakInfo<ValueType>>
const int peakingduck::core::ArrayTypeDynamic = Eigen::Dynamic
template<typename T = DefaultType, int Size = ArrayTypeDynamic>
NumericalData<T, Size> peakingduck::core::combine(const NumericalData<T, ArrayTypeDynamic> &one, const NumericalData<T,
ArrayTypeDynamic> &two)

```

Combine (concatenate) arrays into another.

```

template<typename T = DefaultType, int InputSize = ArrayTypeDynamic, int WindowSize = ArrayTypeDynamic>
NumericalData<T, WindowSize> peakingduck::core::window(const NumericalData<T, InputSize>
&data, int centerindex, int nouter =
5, int ninner = 0, bool includeindex =
true)

```

Given a list of values take *nouter* points either side of the index given and ignore *ninner* points.

Examples:

- a. values = [8, 2, 5, 2, 6, 6, 9, 23, 12] index = 4 nouter = 3 ninner = 0 includeindex = True
=> [2, 5, 2, 6, 6, 9, 23]
- b. values = [8, 2, 5, 2, 6, 6, 9, 23, 12] index = 4 nouter = 3 ninner = 0 includeindex = False
=> [2, 5, 2, 6, 9, 23]
- c. values = [8, 2, 5, 2, 6, 6, 9, 23, 12] index = 4 nouter = 3 ninner = 1 includeindex = True
=> [2, 5, 6, 9, 23]

d. values = [8, 2, 5, 2, 6, 6, 9, 23, 12] index = 4 nouter = 3 ninner = 1 includeindex = False
=> [2, 5, 9, 23]

Therefore:

- ninner >= 0
- ninner <= nouter
- index >= nouter
- index < values.size()

It will clip at (0, len(values))

```
template<typename T = DefaultType, int Size = ArrayTypeDynamic>  
struct peakingduck::core::peakingduck::core::ChunkedThresholdPeakFilter : public peakingduck::core::  
#include <peaking.hpp> Simple threshold local/chunked peak filter.
```

Public Functions

ChunkedThresholdPeakFilter (*T percentThreshold*, size_t *chunkSize* = 10)

NumericalData<*T*, *Size*> go (const *NumericalData*<*T*, *Size*> &*data*) const final override

```
template<typename T, template<typename> class crtpType>  
class peakingduck::core::peakingduck::core::crtp  
#include <crtp.hpp> Represents the base CRTP class to allow objects to have certain abilities in their interface.
```

Public Functions

T &underlying ()

T const &underlying () const

```
template<typename T = DefaultType, int Size = ArrayTypeDynamic>  
struct peakingduck::core::peakingduck::core::GlobalThresholdPeakFilter : public peakingduck::core::  
#include <peaking.hpp> Simple threshold global peak filter.
```

Public Functions

GlobalThresholdPeakFilter (*T percentThreshold*)

NumericalData<*T*, *Size*> go (const *NumericalData*<*T*, *Size*> &*data*) const final override

```
template<typename XScalar, typename YScalar>  
class peakingduck::core::peakingduck::core::Histogram  
#include <spectral.hpp> Represents a basic 1D histogram Energies vs values or Channel vs values.  
Subclassed by peakingduck::core::Spectrum< XScalar, YScalar >
```

Public Functions

```

Histogram()
Histogram(const NumericalData<XScalar> &X, const NumericalData<YScalar> &Y)
Histogram(const Histogram &other)
Histogram(Histogram &&other) = default
Histogram &operator=(const Histogram &other) = default
Histogram &operator=(Histogram &&other) noexcept = default
~Histogram()
NumericalData<XScalar> X() const
NumericalData<YScalar> Y() const

```

Protected Attributes

```

NumericalData<XScalar> _X
NumericalData<YScalar> _Y

```

```

template<typename ValueType = DefaultType, int Size = ArrayTypeDynamic>
struct peakingduck::core::peakingduck::core::IPeakFinder
#include <peaking.hpp> Interface for peak finding algorithms.

```

Operates on numerical data (filtered or unfiltered) Never mutates the input (always const process) returns a list of peaks - PeakList

Subclassed by *peakingduck::core::SimplePeakFinder< ValueType, Size >*

Public Functions

```

~IPeakFinder()
PeakList<ValueType> find(const NumericalData<ValueType, Size> &data) const = 0
Identifies potential peaks in the data.

```

```

template<typename T = DefaultType, int Size = ArrayTypeDynamic>
struct peakingduck::core::peakingduck::core::IProcess
#include <process.hpp> Interface for all process algorithms.

```

Operates on numerical data Never mutates the input (always const process) returns a new numerical array

Subclassed by *peakingduck::core::ChunkedThresholdPeakFilter< T, Size >*, *peakingduck::core::GlobalThresholdPeakFilter< T, Size >*, *peakingduck::core::MovingAveragePeakFilter< T, Size >*, *peakingduck::core::MovingAverageSmoother< T, Size >*, *peakingduck::core::WeightedMovingAverageSmoother< T, Size >*

Public Functions

`~IProcess ()`

`NumericalData<T, Size> go (const NumericalData<T, Size> &data) const = 0`

template<typename **T** = *DefaultType*, int **Size** = *ArrayTypeDynamic*>

struct peakingduck::core::peakingduck::core::IProcessManager
#include <process.hpp> A general process manager interface.

Subclassed by `peakingduck::core::SimpleProcessManager< T, Size >`

Public Functions

`~IProcessManager ()`

`IProcessManager &append (const std::shared_ptr<IProcess<T, Size>> &process) = 0`

`NumericalData<T, Size> run (const NumericalData<T, Size> &data) const = 0`

`size_t size () const = 0`

`void reset () = 0`

template<typename **T** = *DefaultType*, int **Size** = *ArrayTypeDynamic*>

struct peakingduck::core::peakingduck::core::MovingAveragePeakFilter : public peakingduck::core::IProcessManager
#include <peaking.hpp> Simple moving average peak filter.

Public Functions

`MovingAveragePeakFilter (int windowSize)`

`NumericalData<T, Size> go (const NumericalData<T, Size> &data) const final override`

template<typename **T** = *DefaultType*, int **Size** = *ArrayTypeDynamic*>

struct peakingduck::core::peakingduck::core::MovingAverageSmoother : public peakingduck::core::IProcessManager
#include <smoothing.hpp> Simple moving average smoother.

Can we support windowSize given at compile time too? It would certainly help with unit tests.

Public Functions

`MovingAverageSmoother (int windowSize)`

`NumericalData<T, Size> go (const NumericalData<T, Size> &data) const final override`

template<typename **T** = *DefaultType*, int **Size** = *ArrayTypeDynamic*>

struct peakingduck::core::peakingduck::core::NumericalData : private *Array1D<T, Size>*, public *Array1D<T, Size>*
#include <numerical.hpp> Represents a 1-dimensional data structure (basically a 1D Eigen array) Dynamic array - most use cases will be determined at runtime (I am assuming). We don't want anyone to know we are using Eigen beyond this file, since (in theory) it should make it easier to change library if need be. We only really need the array datastructure from Eigen and not much else and instead of reinventing the wheel, we wrap Eigen array.

We wrap this with private inheritance on the Eigen type but there are a lot of methods to expose, easy to add when/if we need them.

Eigen array is pretty good, it has things like sqrt, exp on array coefficients, but we need to extend this to other functions, so we use CRTP to do this.

For all of this, you may ask why not just use Eigen and use an alias? Well for one, we don't need all of Eigen just the array, and not all of the array type (we require a simpler interface). Additionally, at some point we may wish to use another data structure as `std::array` for example. In this case we just change the *NumericalData* class to wrap that instead. If we change the alias this could break existing interfaces and APIs, causing big changes later on. Since this datastructure is fundamental to everything we need to make sure that we have this sorted properly first!

Public Types

```
using value_type = T
using BaseEigenArray = Array1D<value_type, Size>
```

Public Functions

```
template<typename OtherDerived>
NumericalData (const Eigen::ArrayBase<OtherDerived> &other)
NumericalData ()
NumericalData (const std::vector<value_type> &other)
template<typename OtherDerived>
NumericalData &operator= (const Eigen::ArrayBase<OtherDerived> &other)
template<typename OtherDerived>
NumericalData &operator= (const Eigen::EigenBase<OtherDerived> &other)
template<typename OtherDerived>
NumericalData &operator= (const Eigen::ReturnByValue<OtherDerived> &other)
NumericalData &operator= (const std::vector<T> &other)
NumericalData operator+ (const T &scalar) const
NumericalData operator+ (const NumericalData &rhs) const
const NumericalData &operator+= (const NumericalData &rhs)
NumericalData operator- (const T &scalar) const
NumericalData operator- (const NumericalData &rhs) const
const NumericalData &operator-= (const NumericalData &rhs)
NumericalData operator* (const T &scalar) const
NumericalData operator* (const NumericalData &rhs) const
const NumericalData &operator*= (const NumericalData &rhs)
NumericalData operator/ (const T &scalar) const
NumericalData operator/ (const NumericalData &rhs) const
const NumericalData &operator/= (const NumericalData &rhs)
void from_vector (const std::vector<value_type> &raw)
std::vector<value_type> to_vector () const
NumericalData<value_type> slice (int sindex, int eindex) const
NumericalData<value_type> operator () (int sindex, int eindex) const
```

NumericalData **ramp** (const *value_type* &threshold) const

A simple function for filtering values above a certain threshold (>=). This is useful to remove entries that are negative for example.

Returns a new array

NumericalData &**rampInPlace** (const *value_type* &threshold)

A simple function for filtering values above a certain threshold (>=). This is useful to remove entries that are negative for example.

Mutates underlying array

Friends

friend *NumericalData* **operator+** (const *T* &scalar, const *NumericalData* &rhs)

friend *NumericalData* **operator-** (const *T* &scalar, const *NumericalData* &rhs)

friend *NumericalData* **operator*** (const *T* &scalar, const *NumericalData* &rhs)

friend *NumericalData* **operator/** (const *T* &scalar, const *NumericalData* &rhs)

template<class **Derived**>

struct peakingduck::core::peakingduck::core::NumericalFunctions : public peakingduck::core::crtp<Der

#include <numericalfunctions.hpp> To extend the *NumericalData* type with certain numerical abilities, we add it to this using CRTP to keep it in the interface but it doesn't require us to change the underlying data structure.

Public Functions

decltype(auto) **stddev** (int *ddof* = 0) const

Derived **LLS** () const

log(log(sqrt(value + 1) + 1) + 1) Returns a new array

Derived &**LLSInPlace** ()

log(log(sqrt(value + 1) + 1) + 1) Changes the underlying array

Derived **inverseLLS** () const

exp(exp(sqrt(value + 1) + 1) + 1) Returns a new array

Derived &**inverseLLSInPlace** ()

exp(exp(sqrt(value + 1) + 1) + 1) Changes the underlying array

Derived **symmetricNeighbourOp** (const std::function<void> int, int, const *Derived*&, *Derived*&

> &operation, int *order* = 1) const For each element calculate a new value from the symmetric neighbour values at a given order. Take the *i*-order point and the *i*+order point and apply a function to that value End points are not counted (stay as original) - max(0, *i*-j) and min(*i*+j, len(array))

Returns a new array

Derived **gradient** (int *order* = 1) const

For each element calculate the numerical gradient value from the adjacent elements at a given order. Take the *i*-1 point and the *i*+1 point and determine the grad = (array[*i*+1]-array[*i*-1])/2.0. End points are handled differently as first point grad = array[1]-array[0] End points are handled differently as last point grad = array[-1]-array[-2].

For example, given an array: [1. , 2.0, 4.0, 7.0, 11.0, 16.0] The 1-st order gradient would be: [1. , 1.5, 2.5, 3.5, 4.5, 5.] The 2-nd order gradient would be: [0.5, 0.75, 1.0, 1.0, 0.75, 0.5] The 3-rd order gradient would be: [0.25, 0.25, 0.125, -0.125, -0.25, -0.25]

Returns a new array

Derived **&gradientInPlace** (int *order* = 1)

Computes the numerical gradient in place.

See: *NumericalFunctions::gradient*

Mutates underlying array

Derived **midpoint** (int *order* = 1) **const**

For each element calculate the midpoint value from the adjacent elements at a given order. Take the i-order point and the i+order point and determine the average = (array[i-j]+array[i+j])/2.0. End points are not counted (stay as original) - max(0, i-j) and min(i+j, len(array))

For example, given an array: [1, 4, 6, 2, 4, 2, 5] we have the midpoints for order 0: [1, 4, 6, 2, 4, 2, 5] we have the midpoints for order 1: [1, 3.5, 3, 5, 2, 4.5, 5] we have the midpoints for order 2: [1, 4, 2.5, 3, 5.5, 2, 5] we have the midpoints for order 3: [1, 4, 6, 3, 4, 2, 5] we have the midpoints for order 4+: [1, 4, 6, 2, 4, 2, 5]

Returns a new array

Derived **&midpointInPlace** (int *order* = 1)

For each element calculate the midpoint value from the adjacent elements at a given order.

See: *NumericalFunctions::midpoint*

Mutates underlying array

template<class **Iterator**>

Derived **snip** (*Iterator* *first*, *Iterator* *last*) **const**

Sensitive Nonlinear Iterative Peak (SNIP) algorithm for estimating backgrounds ref needed here:

Allows any form of iterations given an iterator

Returns a new array

Derived **snip** (int *niterations*) **const**

Sensitive Nonlinear Iterative Peak (SNIP) algorithm for estimating backgrounds ref needed here:

does via increasing window only (ToDo: need to allow decreasing window)

Deprecate this!

Returns a new array

Derived **&snipInPlace** (int *niterations*)

Sensitive Nonlinear Iterative Peak (SNIP) algorithm for estimating backgrounds.

See: *NumericalFunctions::snip*

Mutates underlying array

template<typename **ValueType** = *DefaultType*>

struct `peakingduck::core::peakingduck::core::PeakInfo`

#include <peaking.hpp> Simple struct for holding peak info.

Stores the: value = value i.e. count, flux index = the corresponding index/channel in the data

Subclassed by *peakingduck::core::PeakInfoWithProp*< *ValueType*, *PropType* >

Public Functions

PeakInfo (*size_t pindex*, *ValueType pvalue*)

Public Members

const *size_t* **index**

const *ValueType* **value**

template<typename **ValueType** = *DefaultType*, typename **PropType** = *DefaultType*>

struct peakingduck::core::peakingduck::core::**PeakInfoWithProp** : **public** peakingduck::core::*PeakInfo*<*Value*>
#include <peaking.hpp> Struct extends basic *PeakInfo* with a property value.

Stores the: property = property i.e. energy, time value = value i.e. count, flux index = the corresponding index/channel in the data

Public Functions

PeakInfoWithProp (*size_t pindex*, *ValueType pvalue*, *PropType pprop*)

Public Members

const *PropType* **property**

template<typename **ValueType** = *DefaultType*, int **Size** = *ArrayTypeDynamic*>

struct peakingduck::core::peakingduck::core::**SimplePeakFinder** : **public** peakingduck::core::*IPeakFinder*
#include <peaking.hpp> Interface for peak finding algorithms.

Operates on numerical data (filtered or unfiltered) Never mutates the input (always const process) returns a list of peaks - *PeakList*

Public Functions

SimplePeakFinder (*ValueType percentThreshold*)

~SimplePeakFinder ()

PeakList<*ValueType*> **find** (**const** *NumericalData*<*ValueType*, *Size*> &*data*) **const override**

Identifies potential peaks in the data based on a simple global threshold of max coefficient.

template<typename **T** = *DefaultType*, int **Size** = *ArrayTypeDynamic*>

struct peakingduck::core::peakingduck::core::**SimpleProcessManager** : **public** peakingduck::core::*IProce*
#include <process.hpp> A simple process manager.

Public Functions

`~SimpleProcessManager ()`

`IProcessManager<T, Size> &append (const std::shared_ptr<IProcess<T, Size>> &process)`
override

`NumericalData<T, Size> run (const NumericalData<T, Size> &data) const` **override**

`size_t size () const` **override**

`void reset ()` **override**

template<typename **XScalar**, typename **YScalar**>

struct peakingduck::core::peakingduck::core::Spectrum: **public** peakingduck::core::Histogram<**XScalar**, **YScalar**>
#include <spectral.hpp> Represents a basic 1D histogram Energies vs values or Channel vs values.

Public Functions

template<class **Iterator**>

`void removeBackground (Iterator first, Iterator last)`

template<class **Iterator**>

`NumericalData<YScalar> estimateBackground (Iterator first, Iterator last) const`

template<typename **T** = *DefaultType*, int **Size** = *ArrayTypeDynamic*>

struct peakingduck::core::peakingduck::core::WeightedMovingAverageSmoother: **public** peakingduck::core::Histogram<**T**, **Size**>
#include <smoothing.hpp> Weighted moving average smoother.

Uses weights determined, with window size = N if N=1, weights=[1] -> [1/N] if N=2, weights=[1,1] -> [1/2, 1/2] if N=3, weights=[1,2,1] -> [1/4, 2/4, 1/4] if N=4, weights=[1,2,2,1] -> [1/6, 2/6, 2/6, 1/6] if N=5, weights=[1,2,3,2,1] -> [1/9, 2/9, 3/9, 2/9, 1/9] ...

Public Functions

WeightedMovingAverageSmoother (int *window size*)

`NumericalData<T, Size> go (const NumericalData<T, Size> &data) const` **final** **override**

3.7.3 peakingduck::io namespace

Defines all I/O - serialization, etc

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constexpr char peakingduck::io::DEFAULTDELIMITER = ''

template<typename **XScalar**, typename **YScalar**, char **delimiter**>

`void peakingduck::io::Deserialize (std::istream &stream, core::Histogram<XScalar, YScalar> &hist)`

Deserialization method for histogram.

Assumes delimited text data in column form of:

channel,lowerenergy,upperenergy,count

template<typename **XScalar**, typename **YScalar**, char **delimiter** = *DEFAULTDELIMITER*>

`std::istream &peakingduck::io::operator>> (std::istream &is, core::Histogram<XScalar, YScalar> &hist)`

3.7.4 peakingduck::util namespace

Defines all utilities (string manip, file IO, etc) of the library.

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bool peakingduck::util::file_exists_quick (const std::string &filename)
uses POSIX stat to check

a function to check if a file exists on disk (fast approach)

Return True if file exists, false otherwise

Parameters

- filename: the name of the file.

bool peakingduck::util::file_exists (const std::string &filename)
uses C file

A function to check if a file exists on disk (not so quick approach, but still fast)

Return True if file exists, false otherwise

Parameters

- filename: the name of the file.

std::string peakingduck::util::read_stream_into_string (std::istream &istream)
Will return a string from a buffered stream.

A function to read a istream as a string

Return A string containing the whole buffer

Exceptions

- ios::failure: if cannot read the buffer

Parameters

- istream: the istream buffer

template<char delimiter, class Container>
void peakingduck::util::split (std::istream &stream, Container &cont)
Split from a stream using single delimiter per line

void peakingduck::util::ltrim (std::string &s)

void peakingduck::util::rtrim (std::string &s)

void peakingduck::util::ltrim (std::string &s, char delimiter)

void peakingduck::util::rtrim (std::string &s, char delimiter)

void peakingduck::util::trim (std::string &s)

template<typename T>
std::vector<T> peakingduck::util::get_window (const std::vector<T> &values, int centerindex,
int nouter = 5, int ninner = 0, bool includeindex
= true)

Given a list of values take nouter points either side of the index given and ignore ninner points.

Examples:

- values = [8, 2, 5, 2, 6, 6, 9, 23, 12] index = 4 nouter = 3 ninner = 0 includeindex = True
=> [2, 5, 2, 6, 6, 9, 23]

- b. values = [8, 2, 5, 2, 6, 6, 9, 23, 12] index = 4 nouter = 3 ninner = 0 includeindex = False
=> [2, 5, 2, 6, 9, 23]
- c. values = [8, 2, 5, 2, 6, 6, 9, 23, 12] index = 4 nouter = 3 ninner = 1 includeindex = True
=> [2, 5, 6, 9, 23]
- d. values = [8, 2, 5, 2, 6, 6, 9, 23, 12] index = 4 nouter = 3 ninner = 1 includeindex = False
=> [2, 5, 9, 23]

Therefore:

- ninner >= 0
- ninner <= nouter
- index >= nouter
- index < values.size()

It will clip at (0, len(values))

```
template<typename IntegerType, IntegerType ibegin, IntegerType iend, IntegerType step = 1>
struct peakingduck::util::peakingduck::util::range
#include <range.hpp> A simple range based struct. Assumes begin, end and step known at compile time
Only used for trivial loops to save doing things like: std::vector<int> indices; for(int i=1, i<5; ++i) indices.push_back(i);.
```

Usage as:

```
auto rn = range<size_t, 1, 5, 1>();
for (auto it=rn.begin(); it!=rn.end(); ++it)
    std::cout << *it << ", ";

1, 2, 3, 4,
```

Public Functions

iterator begin()

iterator end()

iterator begin() const

iterator end() const

struct iterator

Public Types

using value_type = IntegerType

using size_type = std::size_t

using difference_type = IntegerType

using pointer = value_type*

using reference = value_type&

using iterator_category = std::random_access_iterator_tag

Public Functions

```
iterator (IntegerType v)
operator IntegerType () const
operator IntegerType& ()
IntegerType operator* () const
IntegerType const *operator-> () const
iterator &operator++ ()
iterator &operator++ (int)
bool operator== (iterator const &other) const
bool operator!= (iterator const &other) const
```

```
template<typename IntegerType>
```

```
struct peakingduck::util::peakingduck::util::rrange
```

```
#include <range.hpp> A simple range based struct. Assumes begin, end and step not known at compile time Only used for trivial loops to save doing things like: std::vector<int> indices; for(int i=1, i<5; ++i) indices.push_back(i);.
```

Usage as:

```
auto rn = range<size_t>(1,5,1);
for (auto it=rn.begin();it!=rn.end();++it)
    std::cout << *it << ", ";

1, 2, 3, 4,
```

Public Functions

```
rrange (IntegerType ibegin, IntegerType iend, IntegerType step = 1)
```

```
iterator begin ()
```

```
iterator end ()
```

```
iterator begin () const
```

```
iterator end () const
```

```
struct iterator
```

Public Types

```
using value_type = IntegerType
```

```
using size_type = std::size_t
```

```
using difference_type = IntegerType
```

```
using pointer = value_type*
```

```
using reference = value_type&
```

```
using iterator_category = std::random_access_iterator_tag
```

Public Functions

iterator (*rrange*<*value_type*> &*range*, *IntegerType* v)

operator IntegerType () **const**

operator IntegerType& ()

IntegerType **operator*** () **const**

IntegerType **const *operator->** () **const**

iterator &**operator++** ()

iterator &**operator++** (int)

bool **operator==** (*iterator* **const** &*other*) **const**

bool **operator!=** (*iterator* **const** &*other*) **const**

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